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NAVAL AIR SYSTEMS COMMAND  
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**NAWC**

NAVAL AIR WARFARE CENTER

# Mission



*“The Dynamic Avionics Measurement Branch at the NAWC-AD conducts developmental test and evaluation (DT&E) of Navy aircraft and their avionics systems. These systems include radars (fighter/attack, sea surveillance, and AEW), Navigation (IFF, GPS, and INS), communications (voice and data link), reconnaissance systems, antenna systems, forward looking infrared systems and ASW systems. Also included are electronic support measures (ESM) systems, electronic intelligence (ELINT) systems, radar warning receivers, missile warning systems, communications receivers, and antenna patterns. Additionally, NAWC-AD has the mission to conduct performance testing of ECM and ECCM avionics systems including aircraft signature measurements (RCS), radar and communication Jammer-to-Signal (J/S) ratio measurements, Chaff and decoy measurements.”*



# Dynamic Measurement Capabilities

Avionics		Electronic Warfare (EW)	Radar Cross Section (RCS)
<b>Measurement Capabilities</b>	Antenna Pattern	ESM (Airborne Receiver Performance)	Whole Body & Doppler Signature Measurements
	Navigation	Jammer Techniques	Down Range & ISAR Measurements
	Reconnaissance	Receiver Sensitivity	
	Radar	Jammer Duty Cycle	Jammer-to-Signal Ratio
	Navigation	Threat Warning	Chaff & Decoy Measurement
	Communication		
	Reconnaissance	Direction of Arrival Accuracy	
Antenna Patterns			
Real-Time Telemetry Link		Automated Emitter Simulation	Advanced Dynamic Aircraft Measurement System (ADAMS)
Real-Time Avionics Workstation		Local Site Remote Site Mobile Assets	Waveform Data Processing System (WDPS)
Flight Test Systems		Radar and Communication Simulation Automated Control	Real-Time RCS Engineering Workstation Dynamic Flight Programming & Control Signature Data Library



## Infrastructure

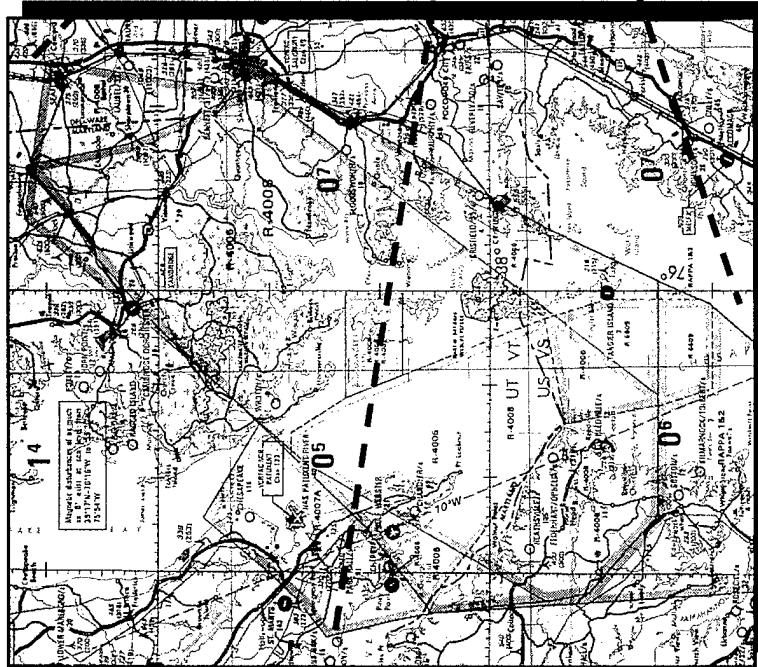
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- ❖ **Flight Test Area**
  - Chesapeake Ranges
  - Offshore Ranges
- ❖ **Range Control Center**
- ❖ **Range Instrumentation Tracking Systems**
  - Time Space Position Information (TSPI)
- ❖ **Real-Time Telemetry Processing System**



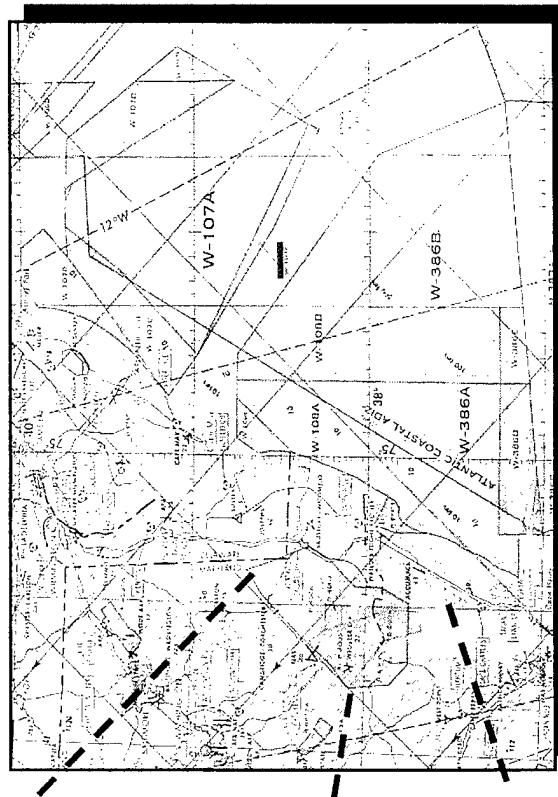
## Flight Test Areas

## Controlled Flight Environment



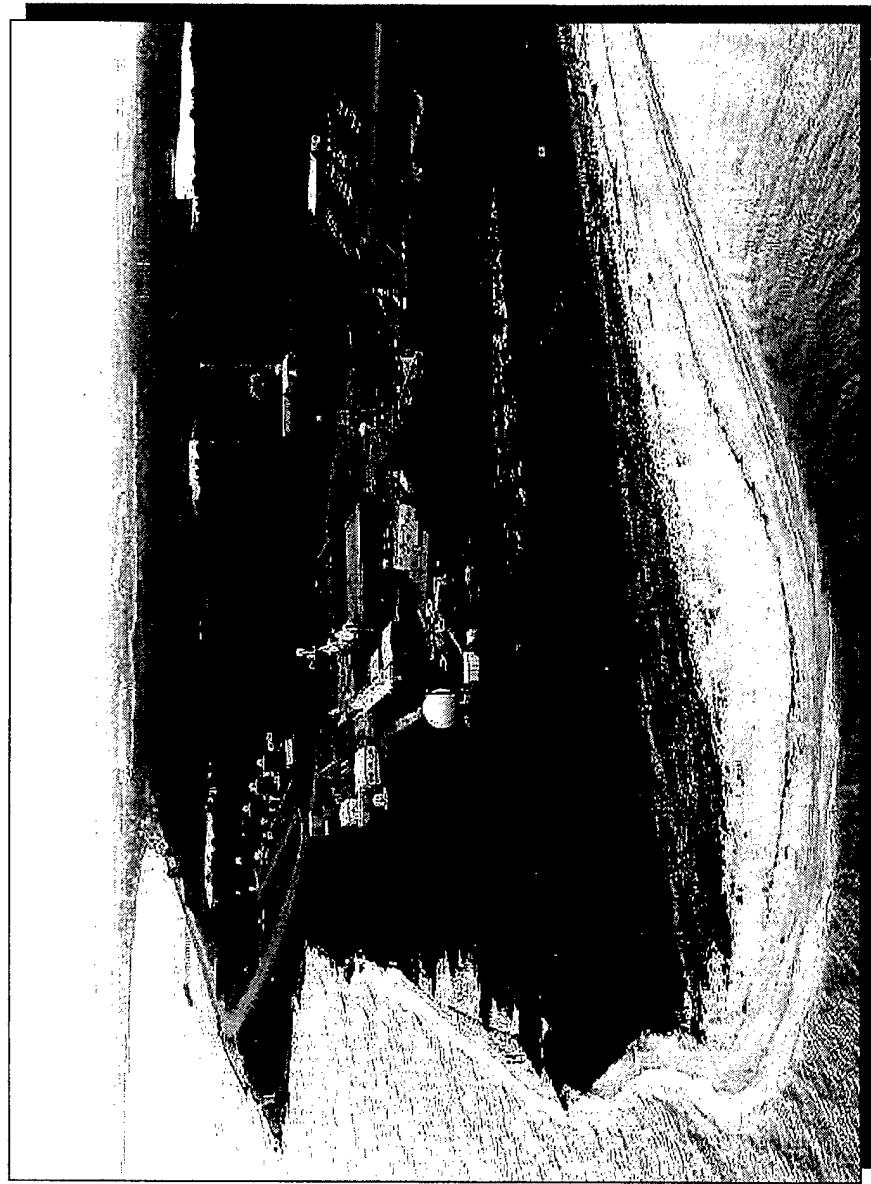
**Chesapeake Ranges**  
**Restricted Areas R-4002/5/6/7/8**  
**2,400 square miles**  
**Surface to 80,000 feet**

## Over Water Supersonic Areas Drop Areas



**Offshore Ranges**  
**Warning Areas W-107/8/386**  
**Approx. 18,000 square miles**  
**Surface to unlimited altitude**

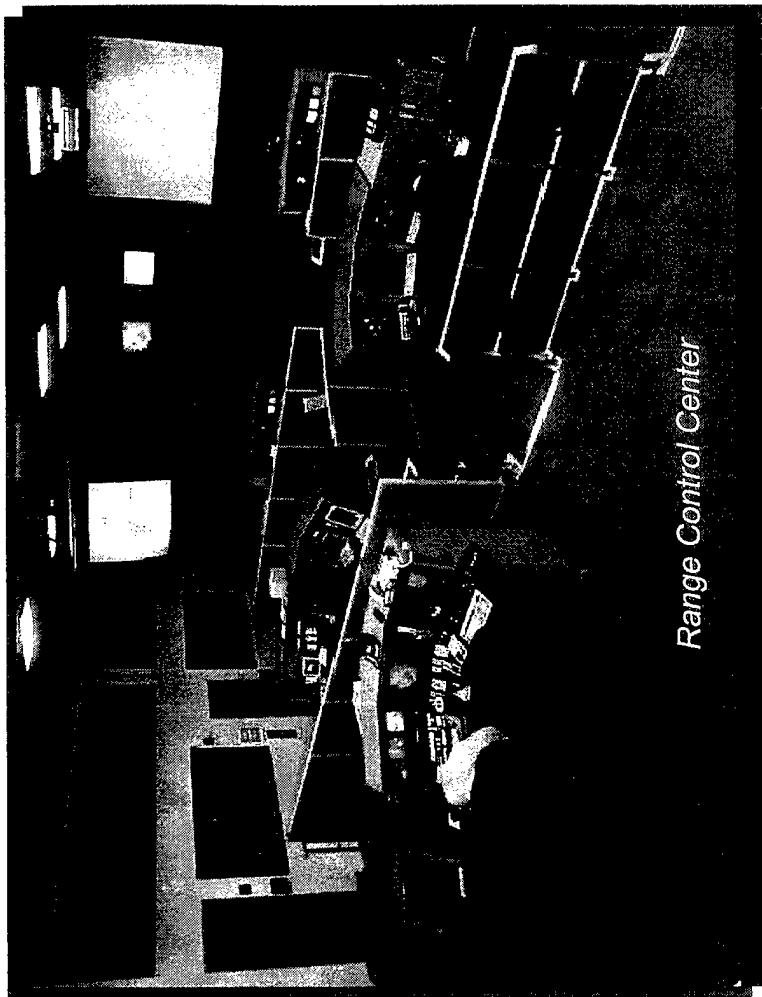
# Cedar Point Facility



# Range Control Center



- ❖ Real-Time Control, Safety, Data Acquisition and Processing of Multiple Test Vehicles (up to 128)
- ❖ Simultaneous Mission Support (5 Mission Control Consoles)
- ❖ Range Safety (Airspace & Surface)
  - Local and Remote Area Surveillance (IFF, FACSFAC VACAPES, Link-11, Surface Radar)
- ❖ Communications Diversity (Video, Voice and Data)
  - Radio, Microwave, Land-line, Fiber Optics, SATCOM
  - Secure Operations
  - DIS/DSI Compatibility With External Connectivity
- ❖ Multisensor Integration
  - Time Space Position Information (TSPi)
  - Video (High Resolution)
  - Film (5 to 400 Frames Per Second)
  - Audio
  - Meteorological Data



Range Cntr Cntr.ppt



# Tracking Instrumentation Diversity

## ❖ Radar

- Single and Multiple Object
- Cooperative and Noncooperative
- Frequency and Geographic Diversity

## ❖ Electro-Optical

- Video and Film Theodolites
- Automatic Laser Tracking System (ALTS)
- Infrared (IR)

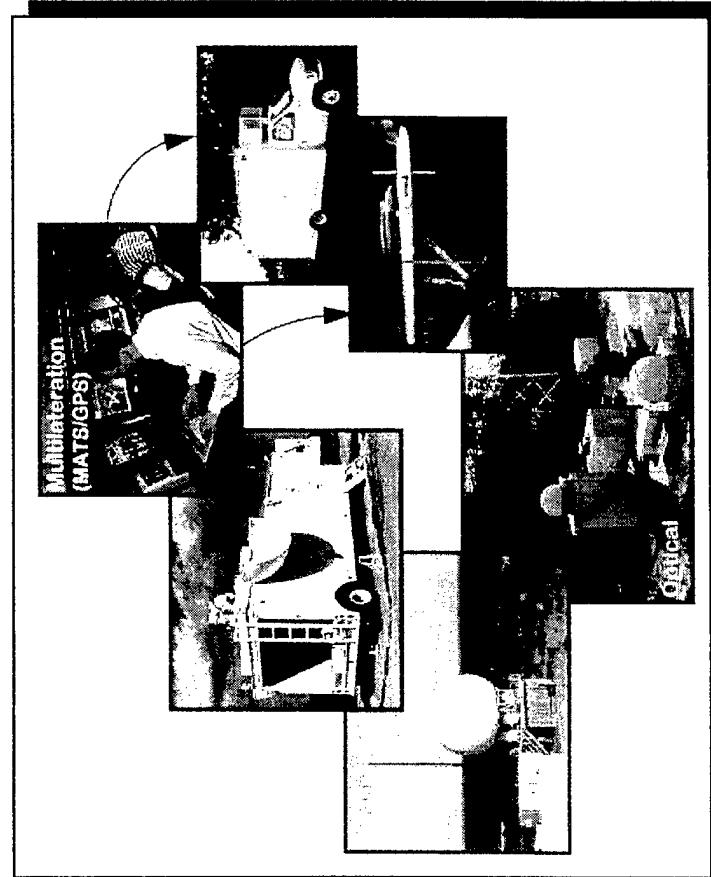
## ❖ Multilateration Tracking System (MATS)

- Mid-Atlantic Tracking System (MATS)
- Global Positioning System (GPS)

- Large area coverage
- Multiple participants
- Over the horizon
- Land, air and sea coverage

## ❖ Area Surveillance

- IFF
- FACSFAC
- Link II
- Surface





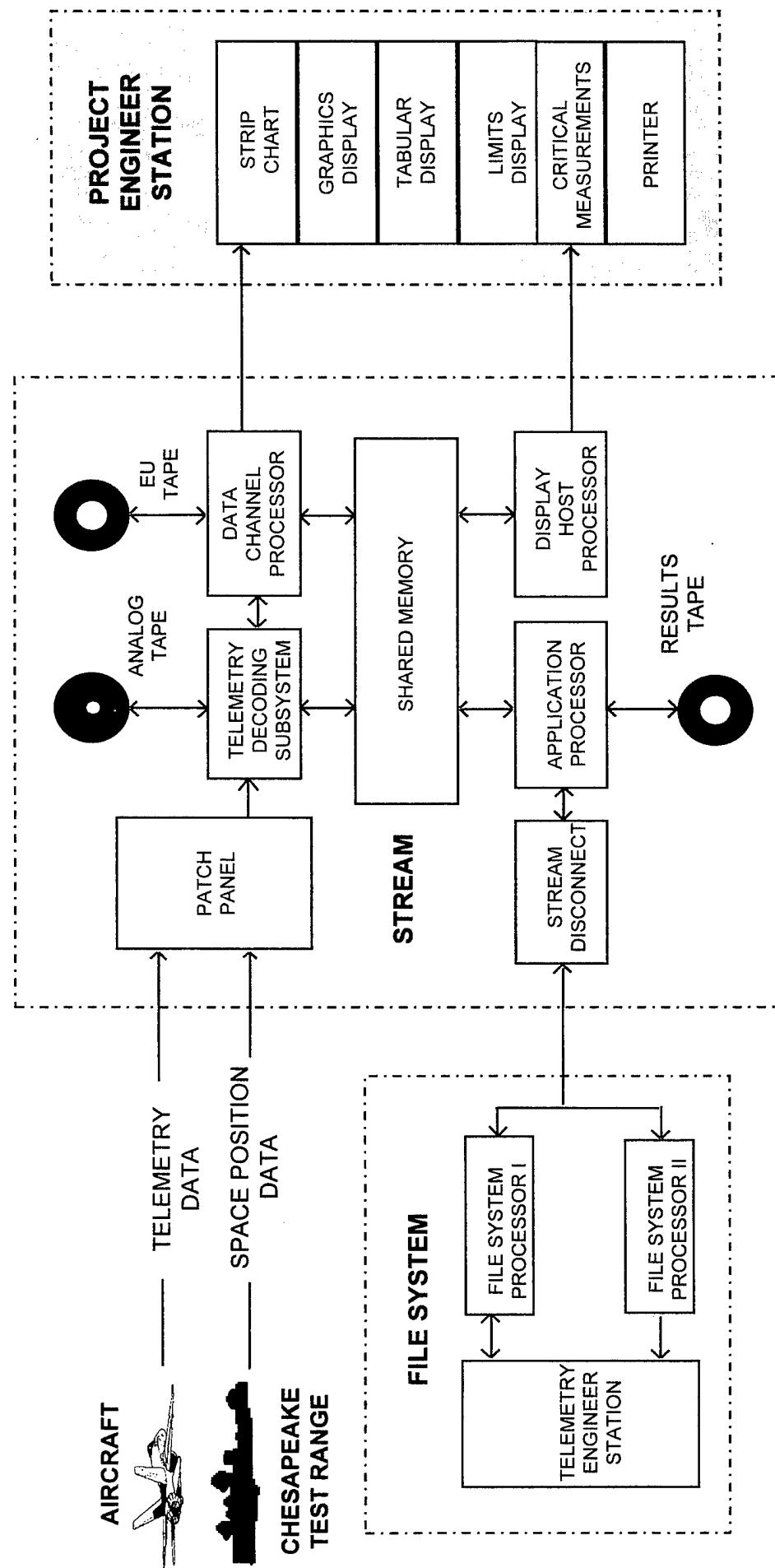
# Range Tracking Systems Performance

Tracking System	Tracking Range	Accuracy (RMS)	Special Considerations
ALTS (portable) Automatic Laser Tracking System (2)	8.5 Miles	Range: 3 feet Angle: 0.1 mils	Requires retroreflector on target
THEODOLITE Range * w/Laser Ranger **	15 Miles (max)	@ Hooper Target (4 miles) X,Y,Z: 15 feet (Real-time) X,Y,Z: 3 feet (Post-flight film reading)	Visual observation Man in the Loop 4 Fixed Contraves 1 Mobile Contraves
CEDAR POINT RIR-778 Radars (3)	Skin 100 Miles Beacon 200 Miles	Range: 10 feet Angle: 0.1 mils	Nth time around trackers 3 Radars
CEDAR POINT AN/FPQ-17 Radar (MIR)	Skin 100 Miles Beacon 200 Miles	Range: 10 feet Angle: 0.25 mils	16 tracks Skin 2 tracks Beacon
WALLOPS RADARS FPS-16, FPQ-6	200 Miles	Range: 6 feet Angle: 0.1 mils	3 Radars linked into ATR
GPS with High Dynamic Instrumentation Set (HDIS) 15 External Pods 5 Internal Advanced Range Data System (ARDS) plates	600 miles w/ relays or Line of Sight	X&Y: 6 feet Z: 10 feet X&Y: 21 feet Z: 35 feet X&Y: 19 feet Z: 32 feet X&Y: 42 feet Z: 70 feet	Pitch $\beta$ 0.3 Roll $\beta$ 0.5 Heading $\beta$ 0.3 H. Position $\tau$ 4.0 V. Position $\tau$ 6.0 H. Velocity $f$ 0.7 V. Velocity $f$ 0.7

\* Requires three sites for solution

\*\* Single Mobile Theodolite has real-time accuracy  
 $\beta$  - degrees  $\tau$  - feet  $f$  - ft/sec

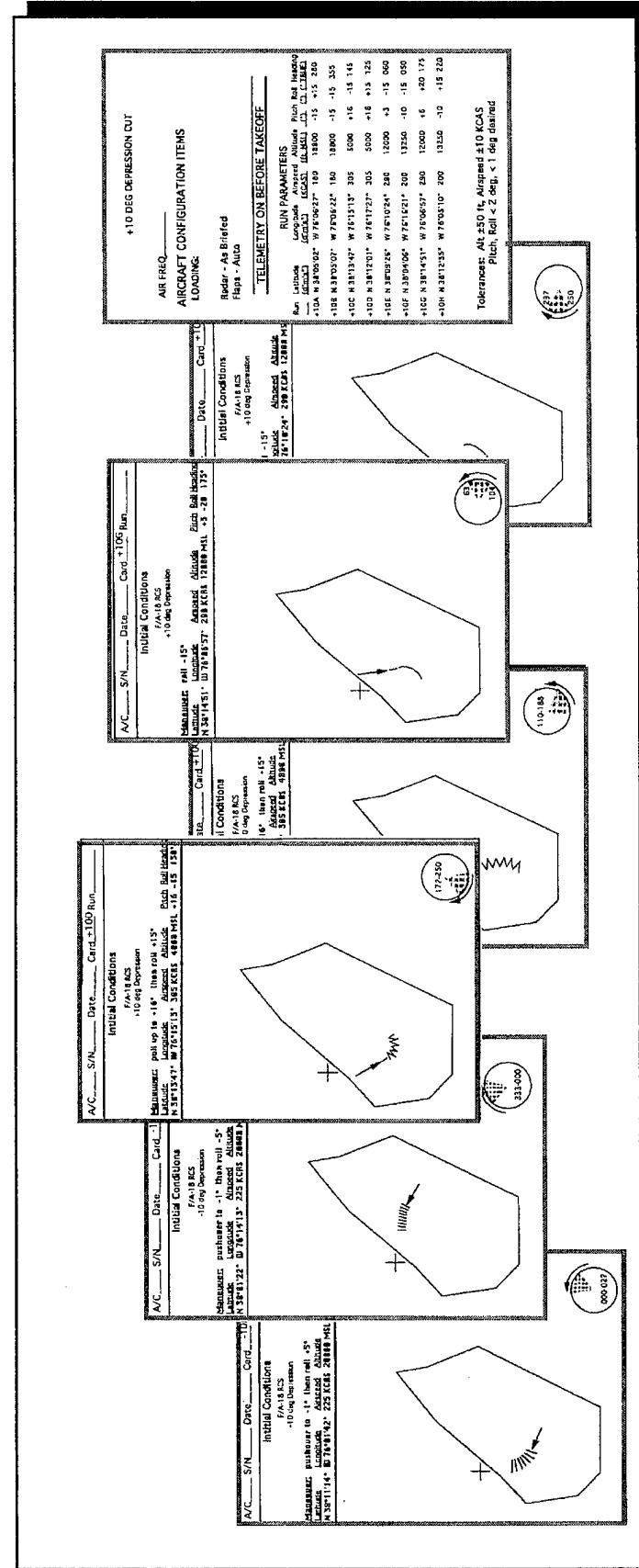
# Real-Time Telemetry Processing System (RTPS)





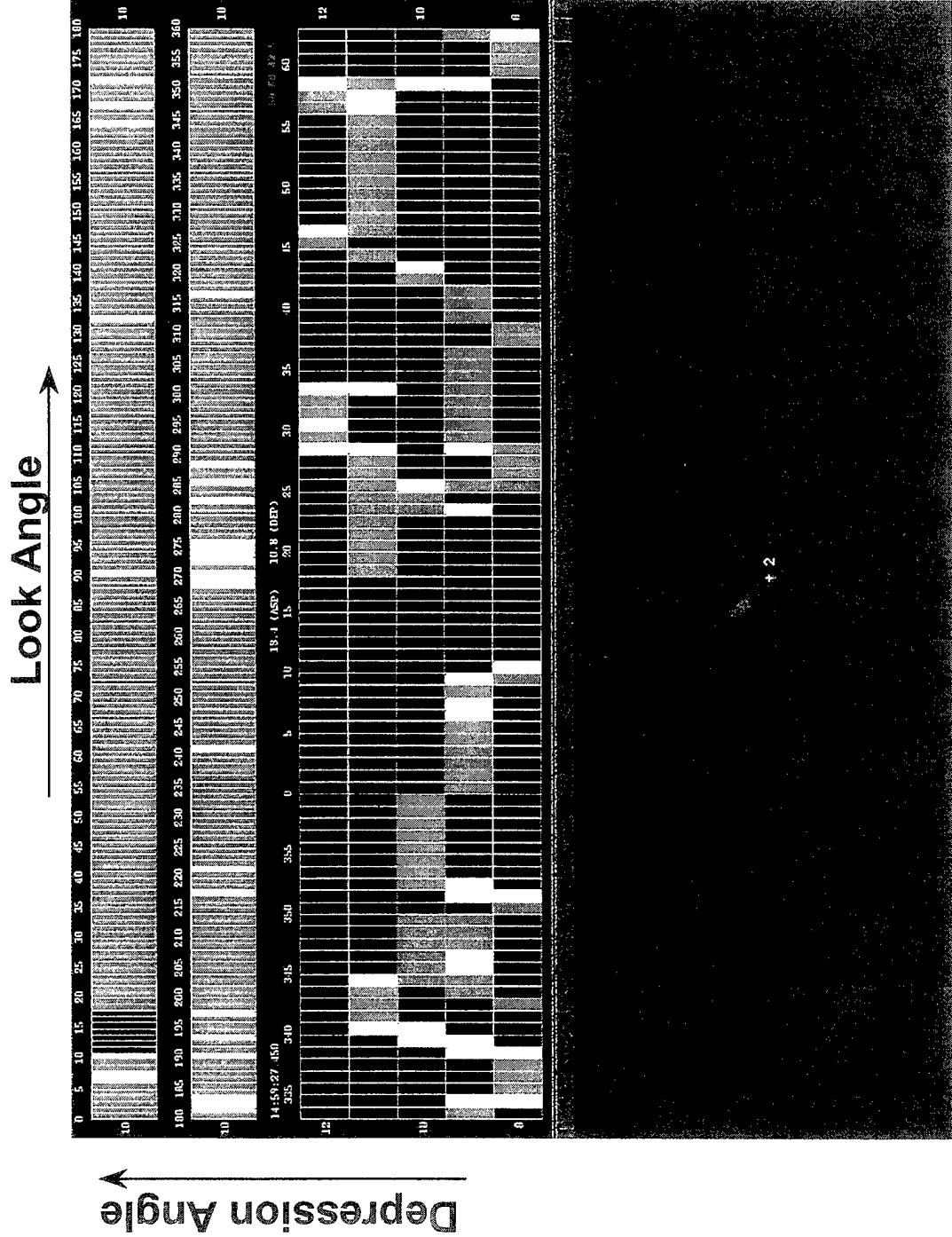
# Dynamic Collection Flight Control

- ❖ Computer-Generated Flight Profiles
- ❖ Pre-Fly RCS Maneuvers
  - Maximizes Data Collection
  - Minimizes Flight Time
- Employs Manned Flight Simulator at ACETEF
- ❖ Real-Time Data Bin Filling Routine





# Aircraft Aspect and BIN Filling Display



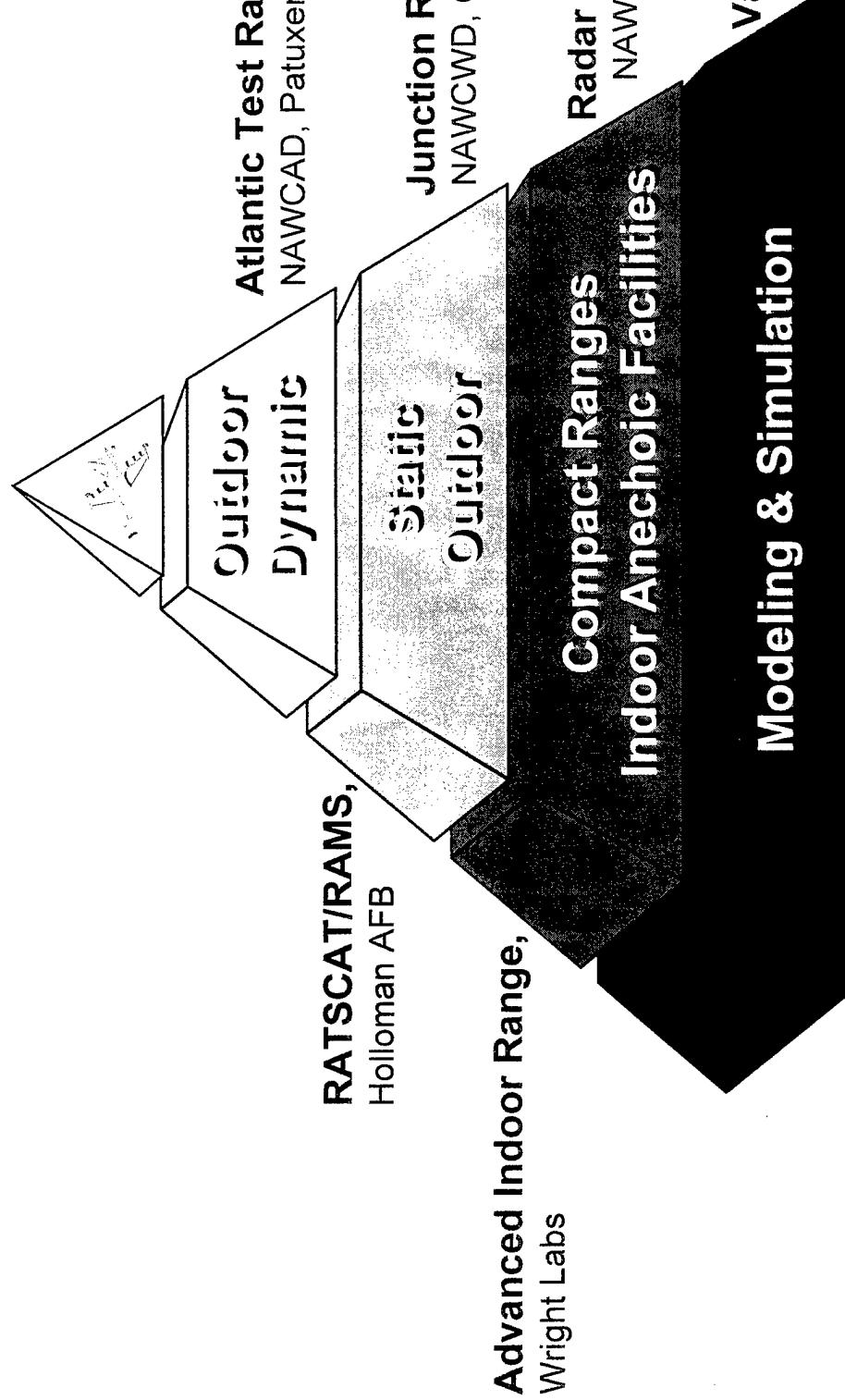
# Dynamic In-Flight Radar Cross Section Measurements

- ❖ Whole Body & Doppler Signature Measurements
- ❖ Down Range & ISAR Measurements
- ❖ Jammer-to-Signal Ratio
- ❖ Chaff & Decoy Measurement





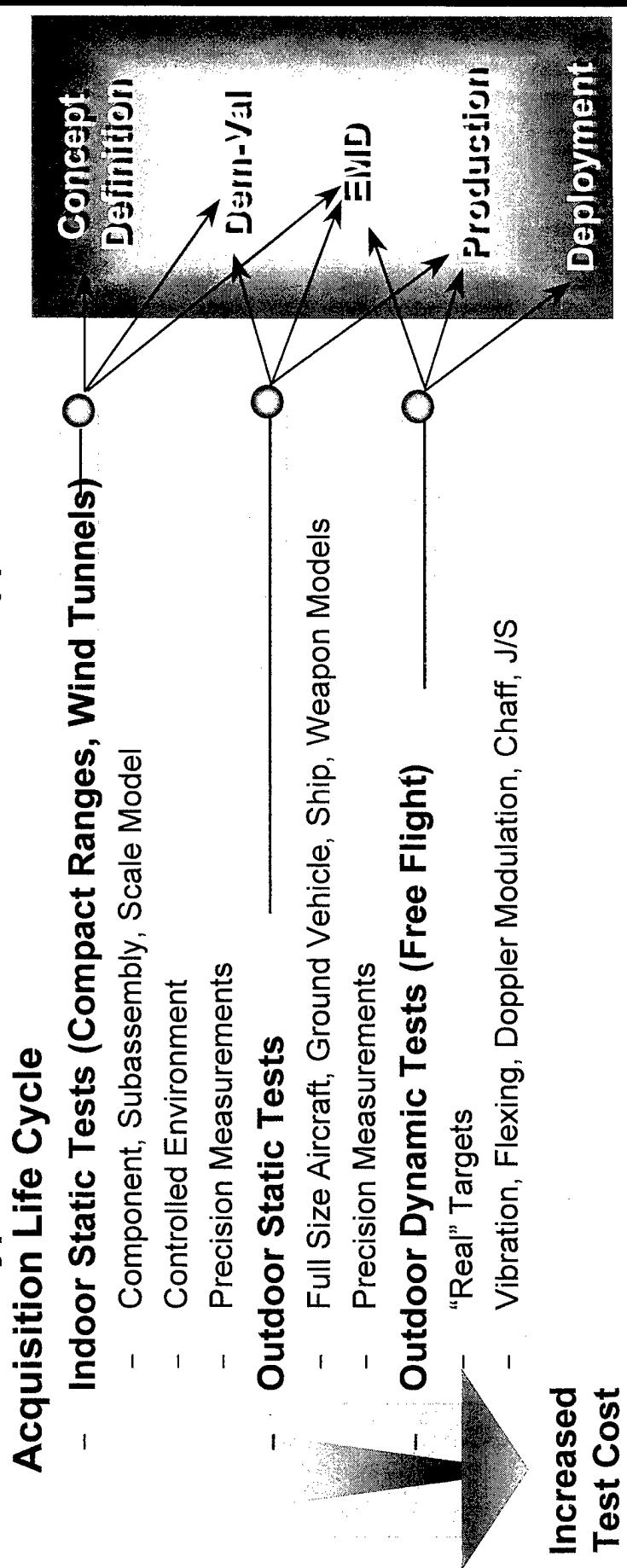
# Air Vehicle RCS Measurement Process



# Signature Measurements Support DoD Acquisition Process



- ❖ Signature Measurements Required for Vehicle & Munitions Development
- ❖ Different Vehicles & Different Environments (Land, Air, Sea, Space)
- ❖ Different Types of Measurement Facilities Support the “Cradle-to-Grave” Acquisition Life Cycle





# Why Dynamic In-Flight RCS Measurements?

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- ❖ Full-Size Actual Test Article
- ❖ Target Scintillation
  - Engine Modulation
  - Propeller Modulation
  - Antenna Rotation
  - Vehicle Vibration
  - Vehicle Flexing
- ❖ Towed / Expendable Decoys
- ❖ Jammer-to-Signal
- ❖ Chaff



# Dynamic RCS Measurement Features

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- ❖ 80 Simultaneous Measurements

- 150 MHz to 35 GHz
- 500 Hz to 200 kHz Pulse Sampling Rate
- Vertical & Horizontal Polarization
- +1.1/-1.5 dB (NIST Report NISTR 5073 of Feb 98)
- 1 Degree Aspect Resolution in both AZ & EL

- ❖ Coherent and Non-Coherent Measurement Systems (ADAMS & WDPSS)

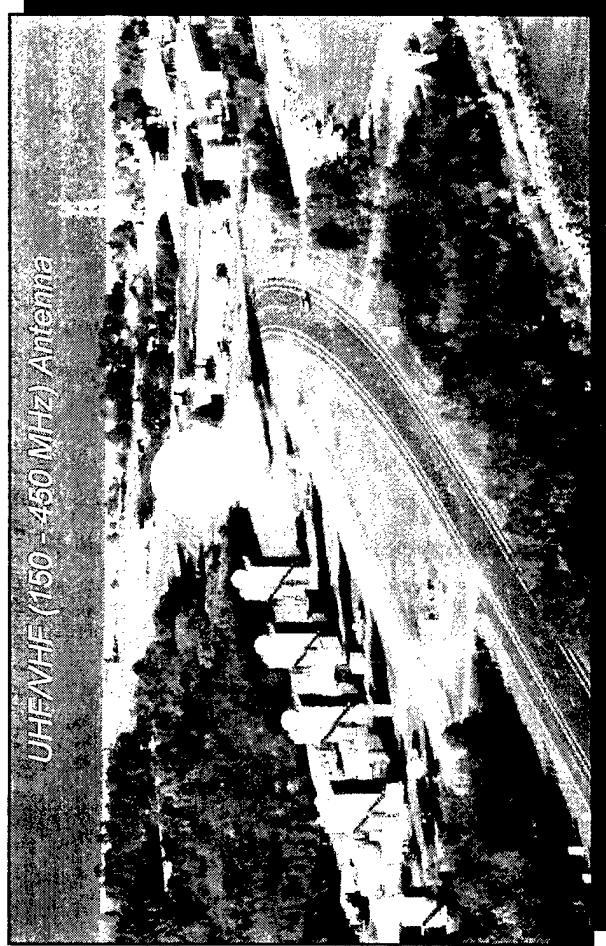
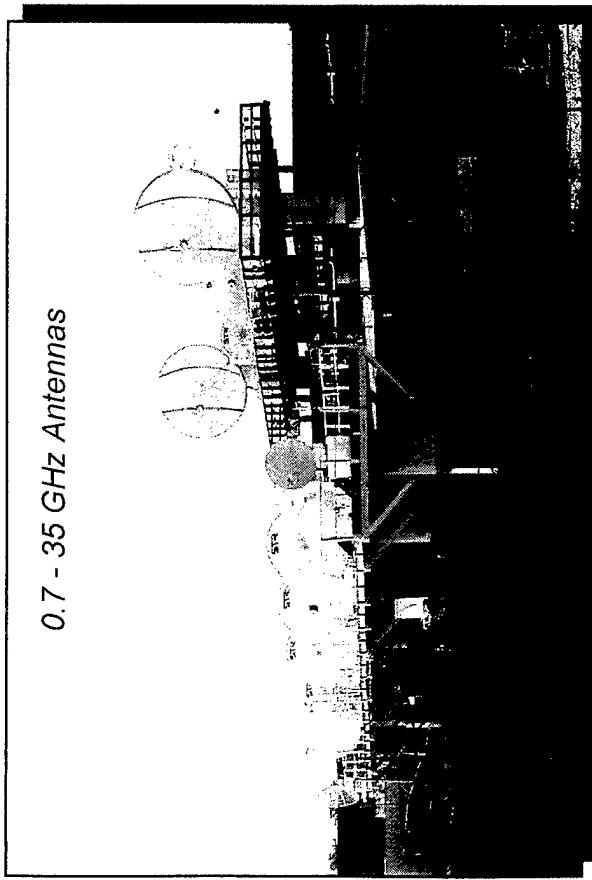
- ❖ Real-Time Processing & Display of Polar Plots

- ❖ Complete Statistical Reports Including Probability Density Function (PDF)

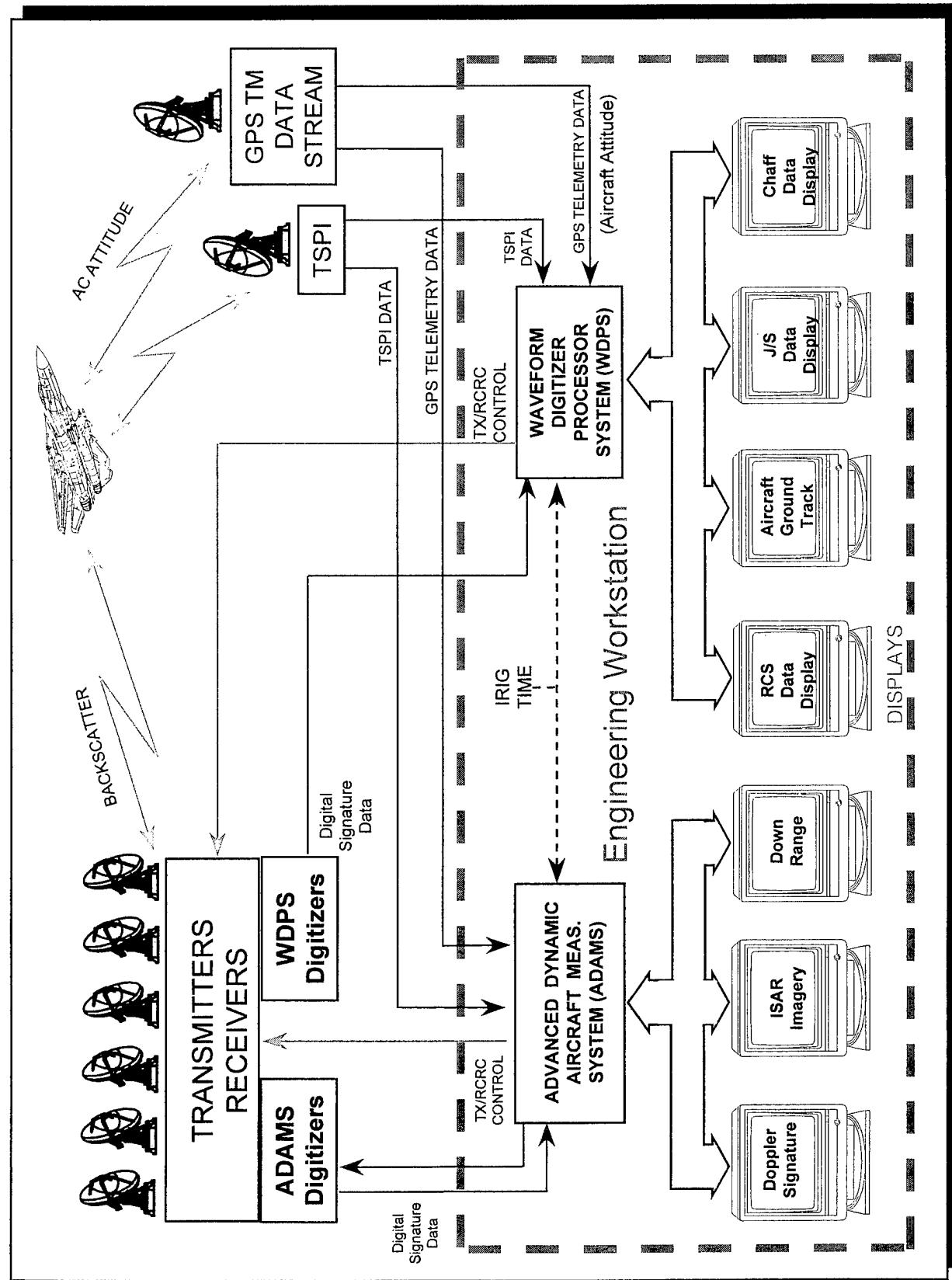
- ❖ Dynamic Flight Control



# RCS Measurement Antenna Sites



# RCS Flight Test System





# Real-Time RCS Flight Test System



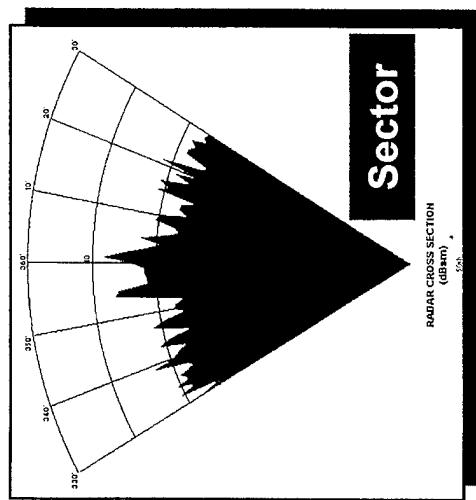
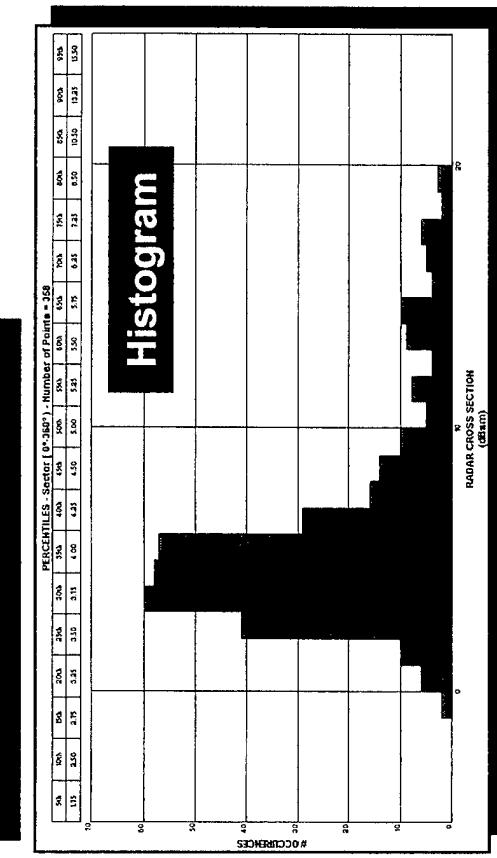
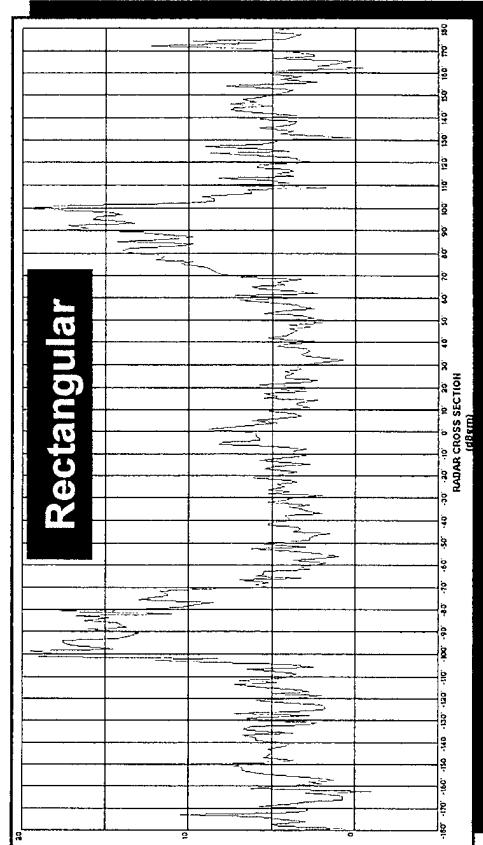
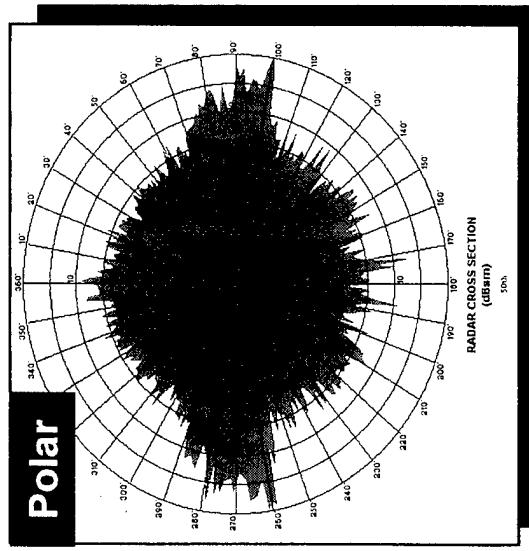
*RCS Engineering Workstation*

# Dynamic Signature Capabilities



- ❖ Whole Body RCS Signature Measurements
- ❖ Doppler Signature Measurements
  - Blades
  - Jet Engine Modulation (JEM)
- ❖ Precision Down Range Profiles
- ❖ ISAR Imagery
- ❖ Jammer-to-Signal Ratio Measurements
- ❖ Chaff Measurements
  - Growth Rate (SP)
  - RF Spectrum
  - Shadow Graph
- ❖ Decoy Measurements (Towed and Expendable)
- ❖ Extensive Signature Data Library

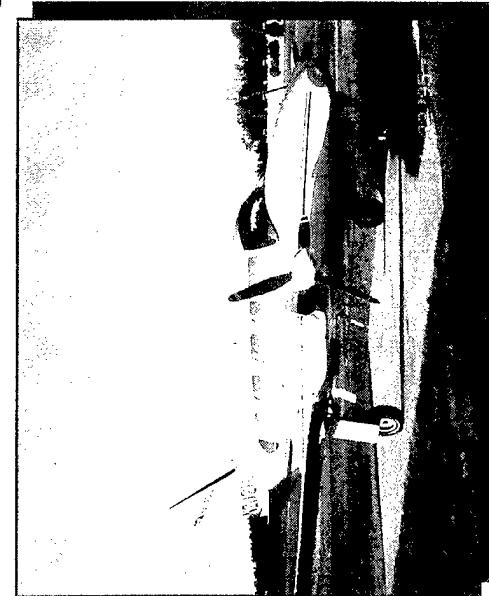
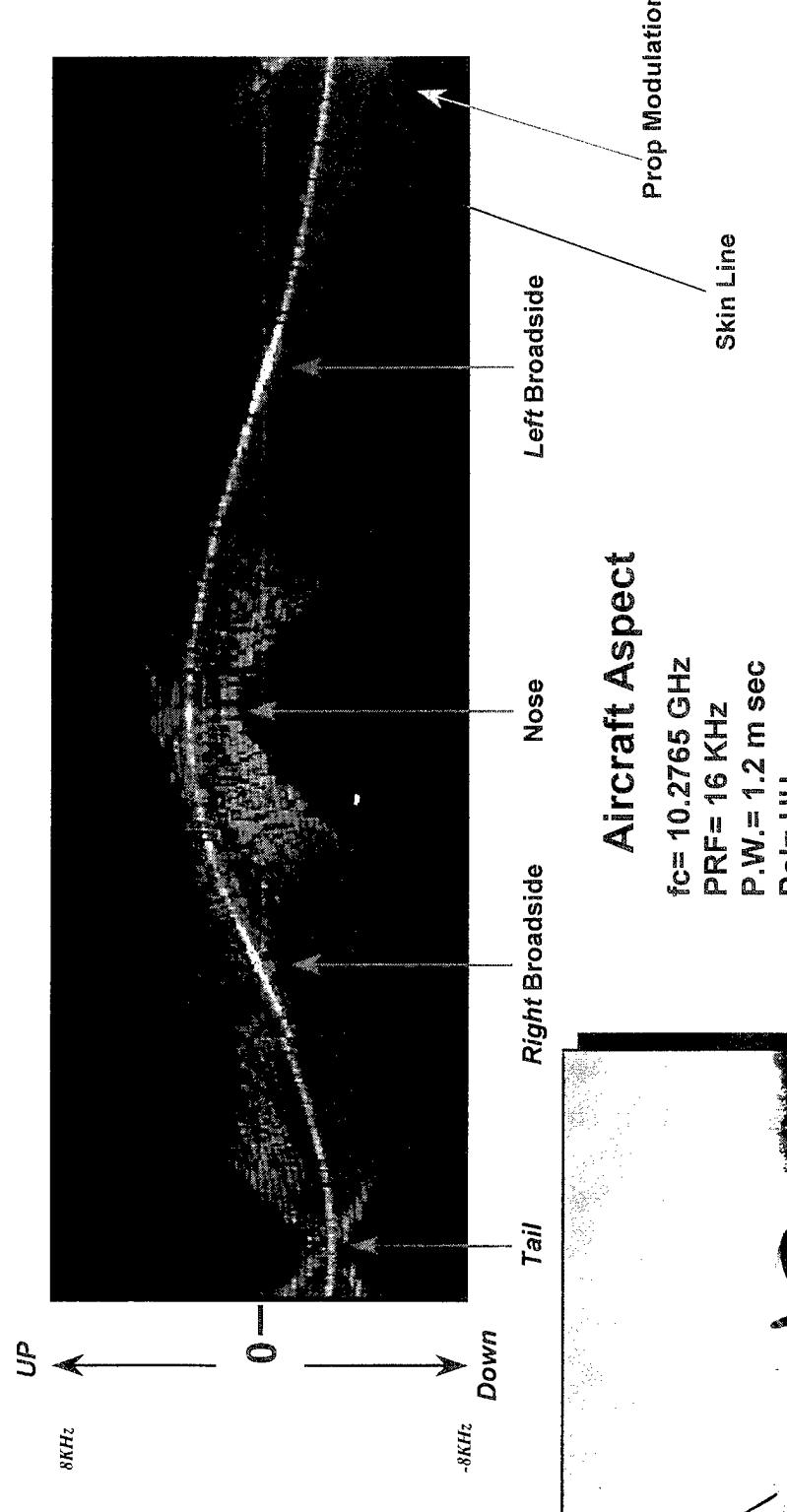
# Whole Body RCS Signature Measurements Sample Data Products





# Doppler Signature Measurements Sample Data Product - Blade Modulation

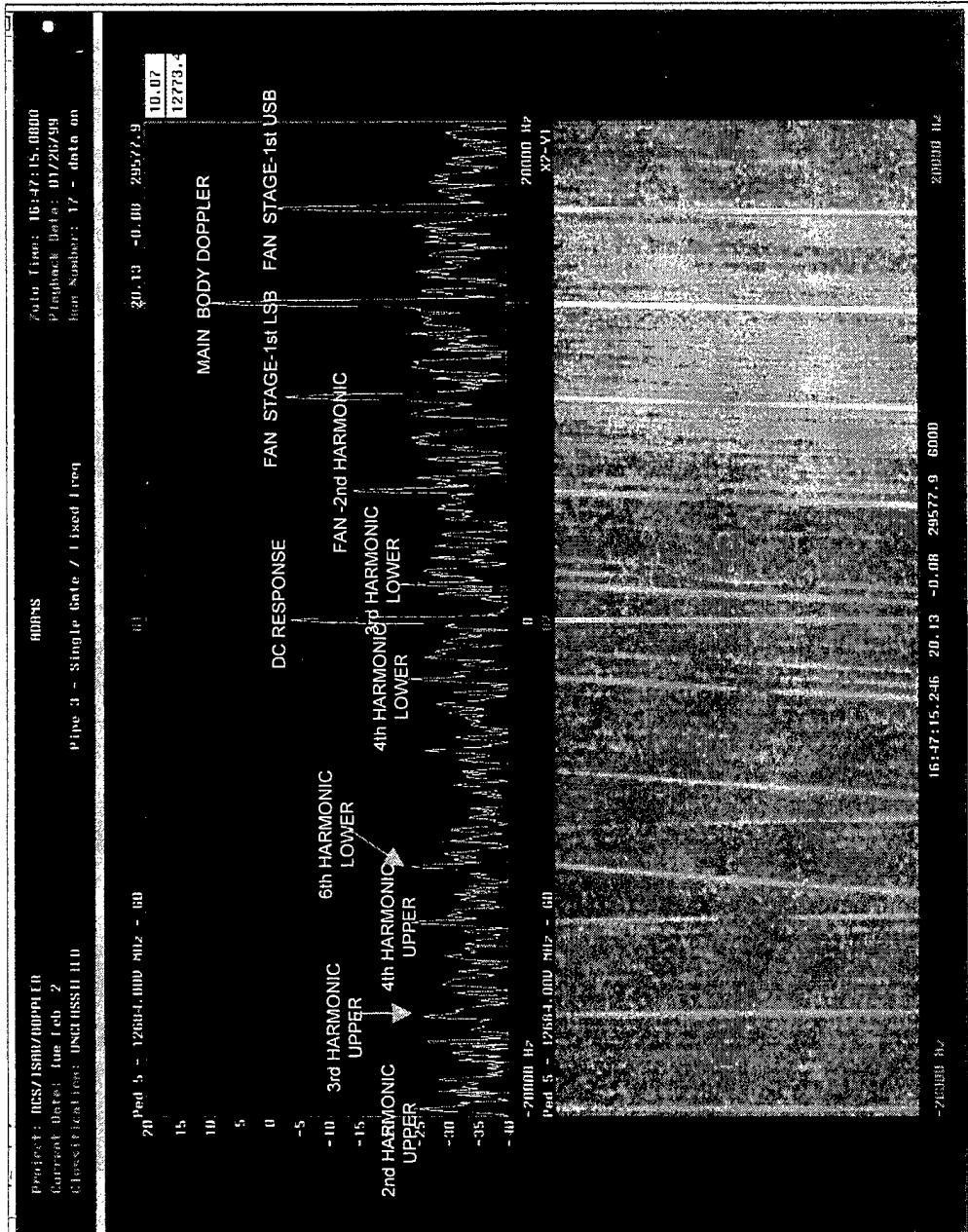
## Example: Piper Navajo



# Doppler Signature Measurements Sample Data Product - JEM Spectrum/Histogram



## Example: Learjet

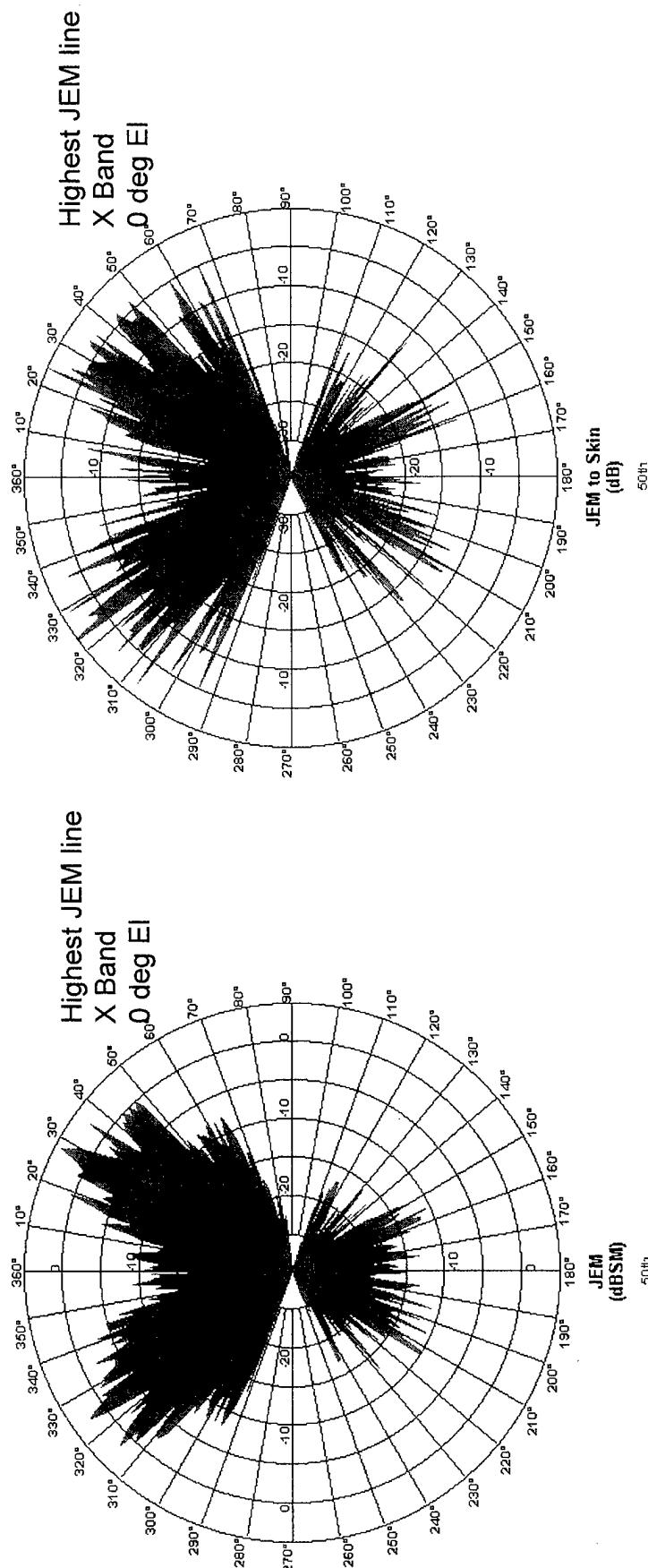




# Doppler Signature Measurements Sample Data Product - JEM vs Aspect

Example: Lear 36

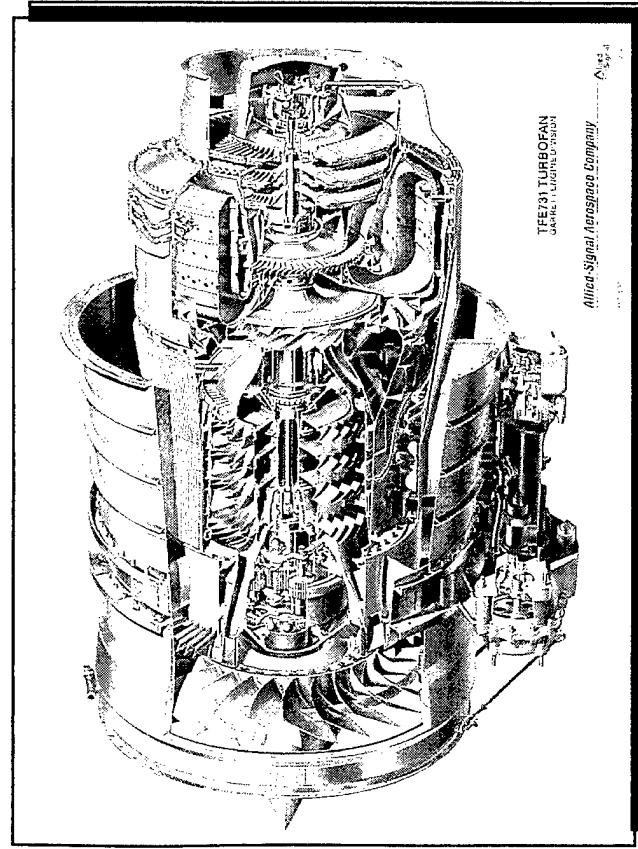
## JEM to Skin Ratio



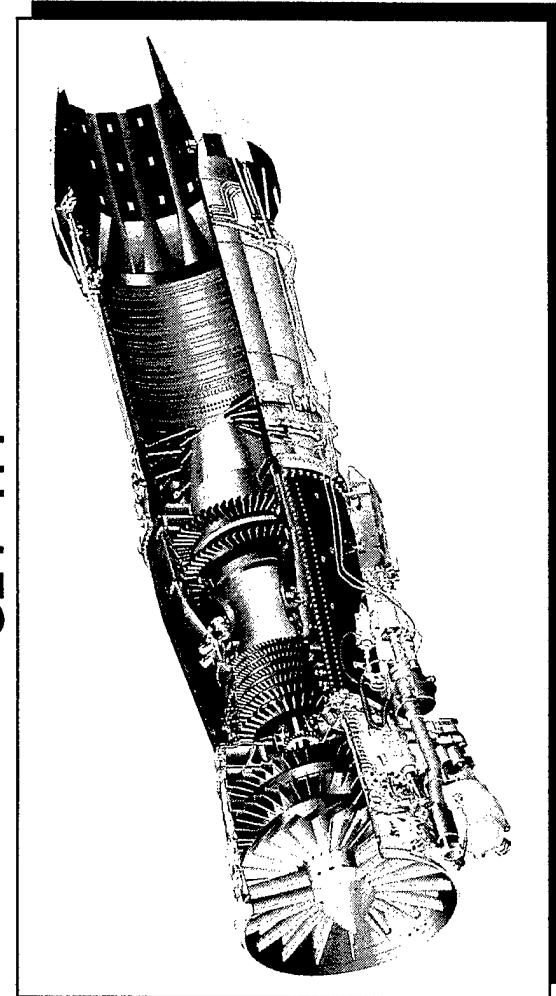


## Different Engines = Different JEM

### Lear 36 Engine



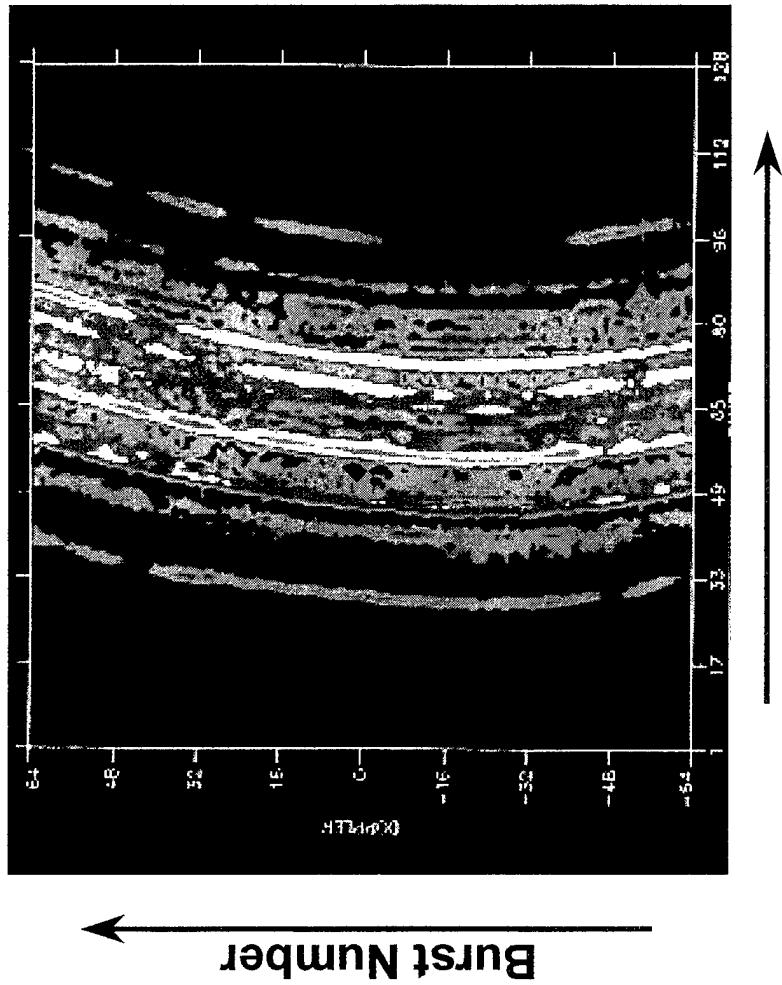
**F-18E/F Engine  
GE F-414**





# Precision Down Range Profiles

Example: Piper Navajo



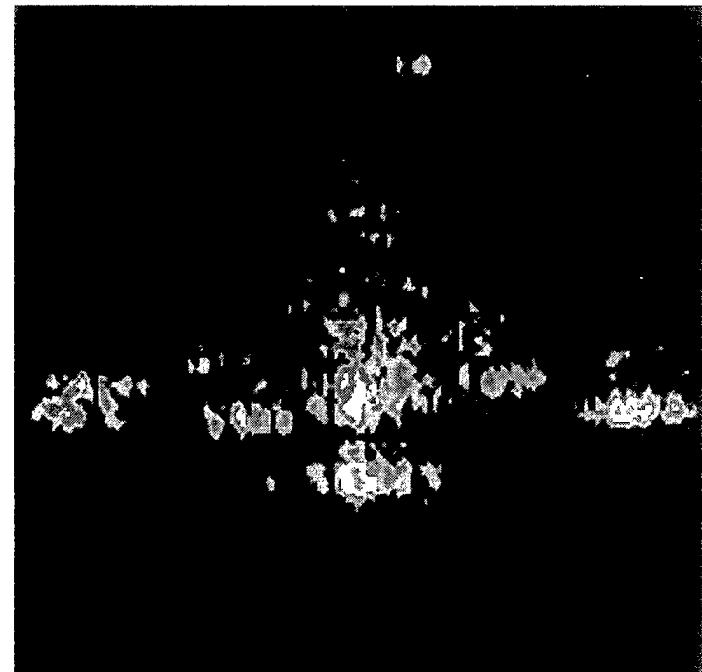
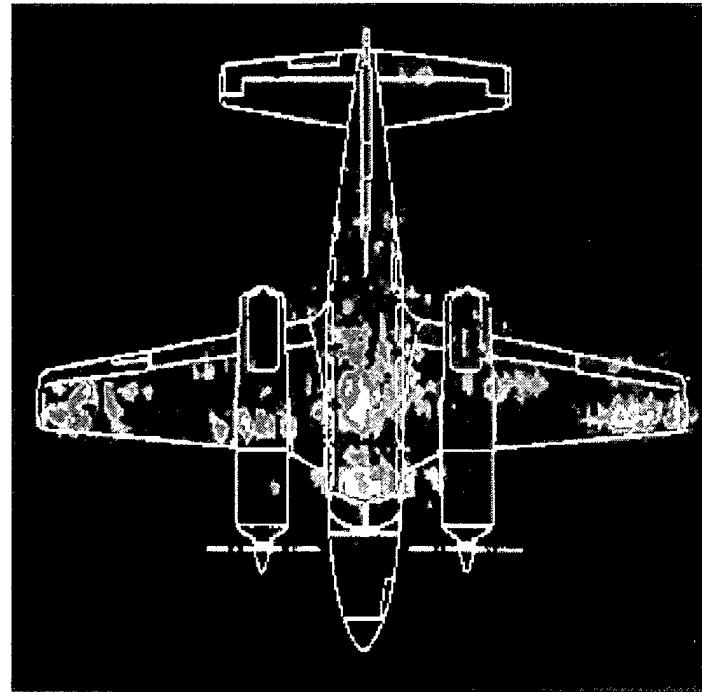
Down Range

$f_c = 10.2765 \text{ GHz}$       Res. = 6"  
 $\text{PRF} = 10 \text{ KHz}$        $D_f = 950 \text{ MHz}$   
 $P.W. = 1.2 \text{ m sec}$       # steps = 128  
Pol = HH



# ISAR Imagery

## Example: Piper Navajo



$f_c = 10.2765 \text{ GHz}$   
 $\text{PRF} = 10 \text{ kHz}$   
 $\text{P.W.} = 1.2 \text{ m sec}$   
 $\text{Pol} = \text{HH}$

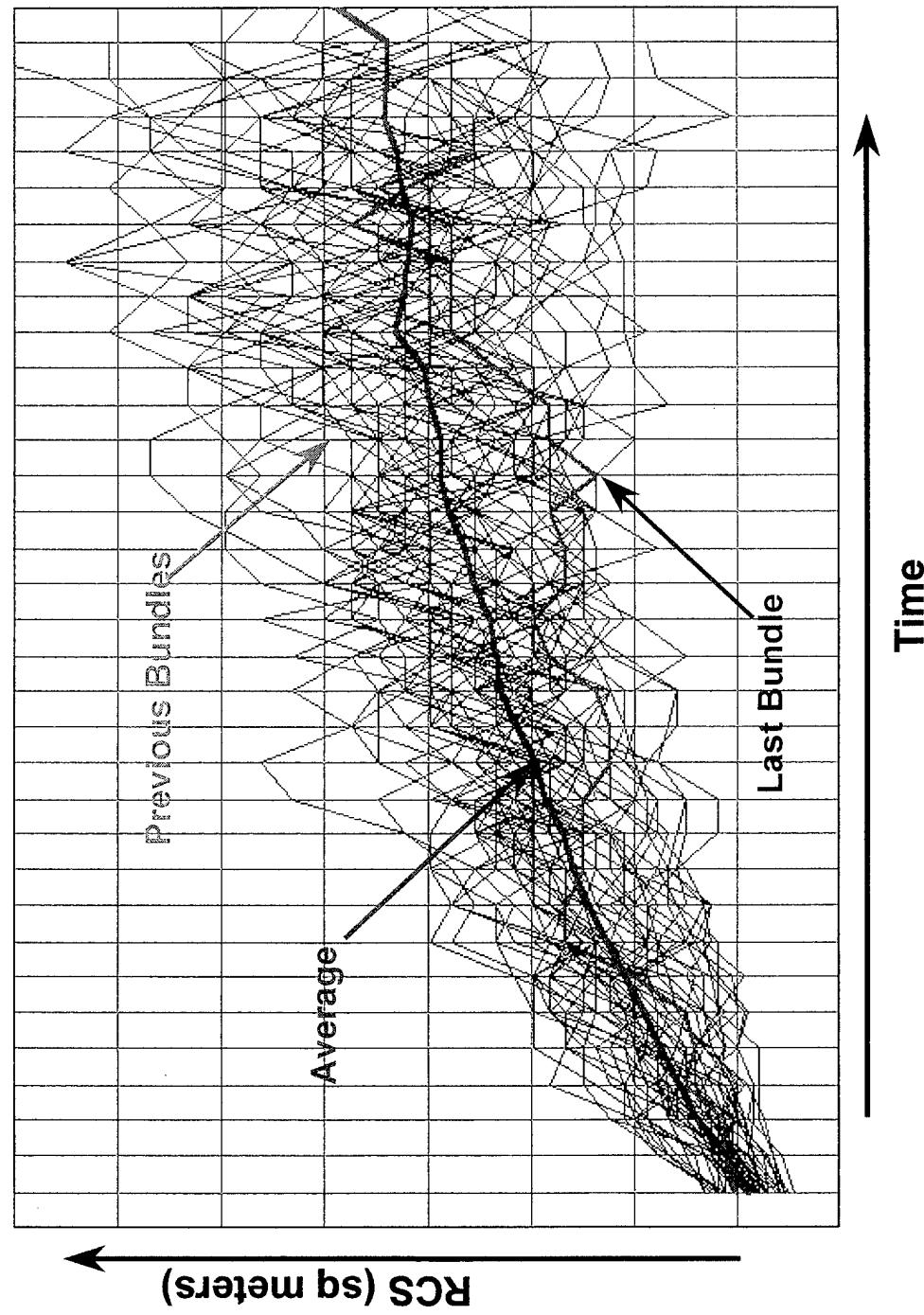
Down Range

$\text{Res.} = 6''$   
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 $\# \text{ steps} = 128$

Down Range

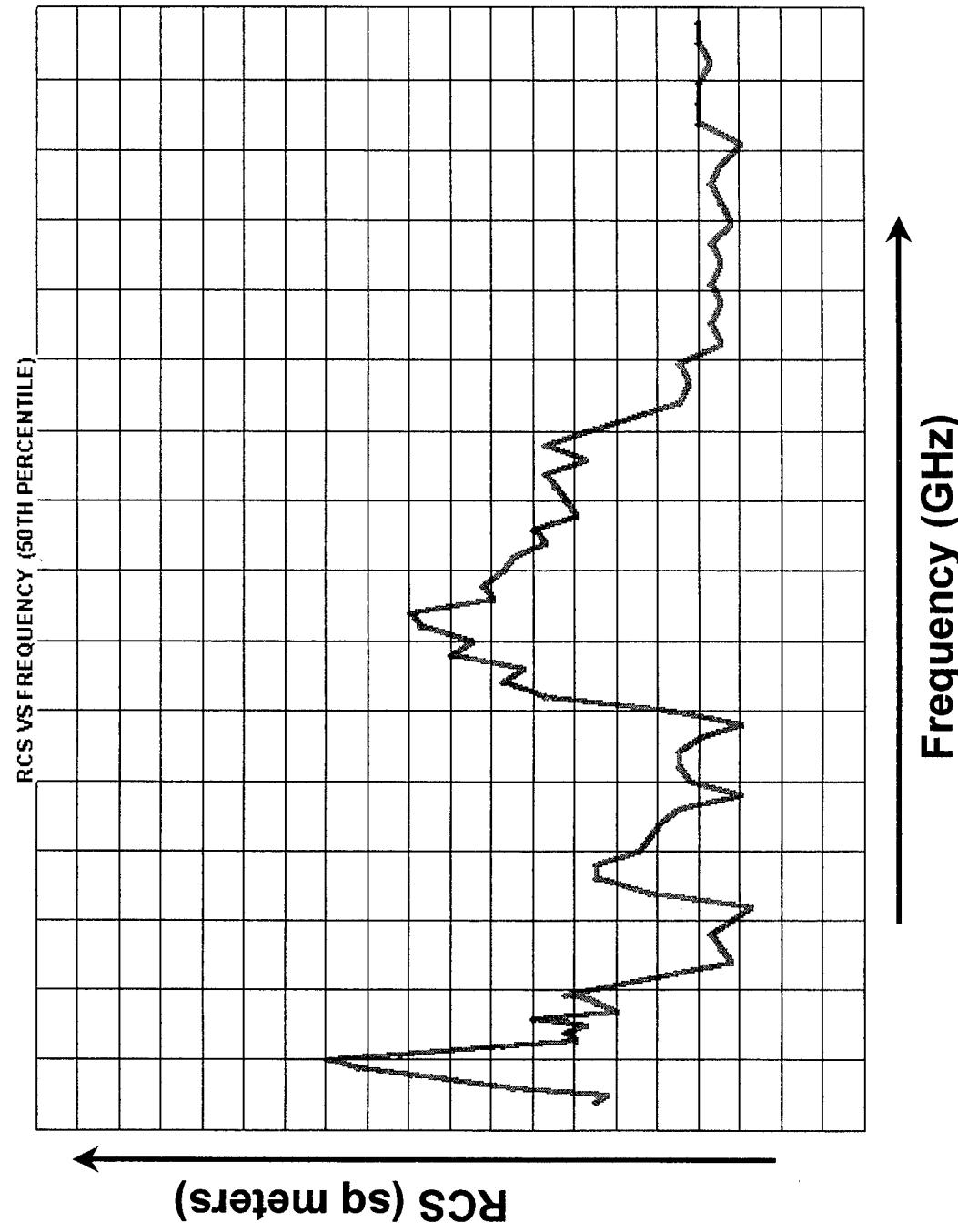
## Chaff Measurements

### Sample Data Product - Growth Rate



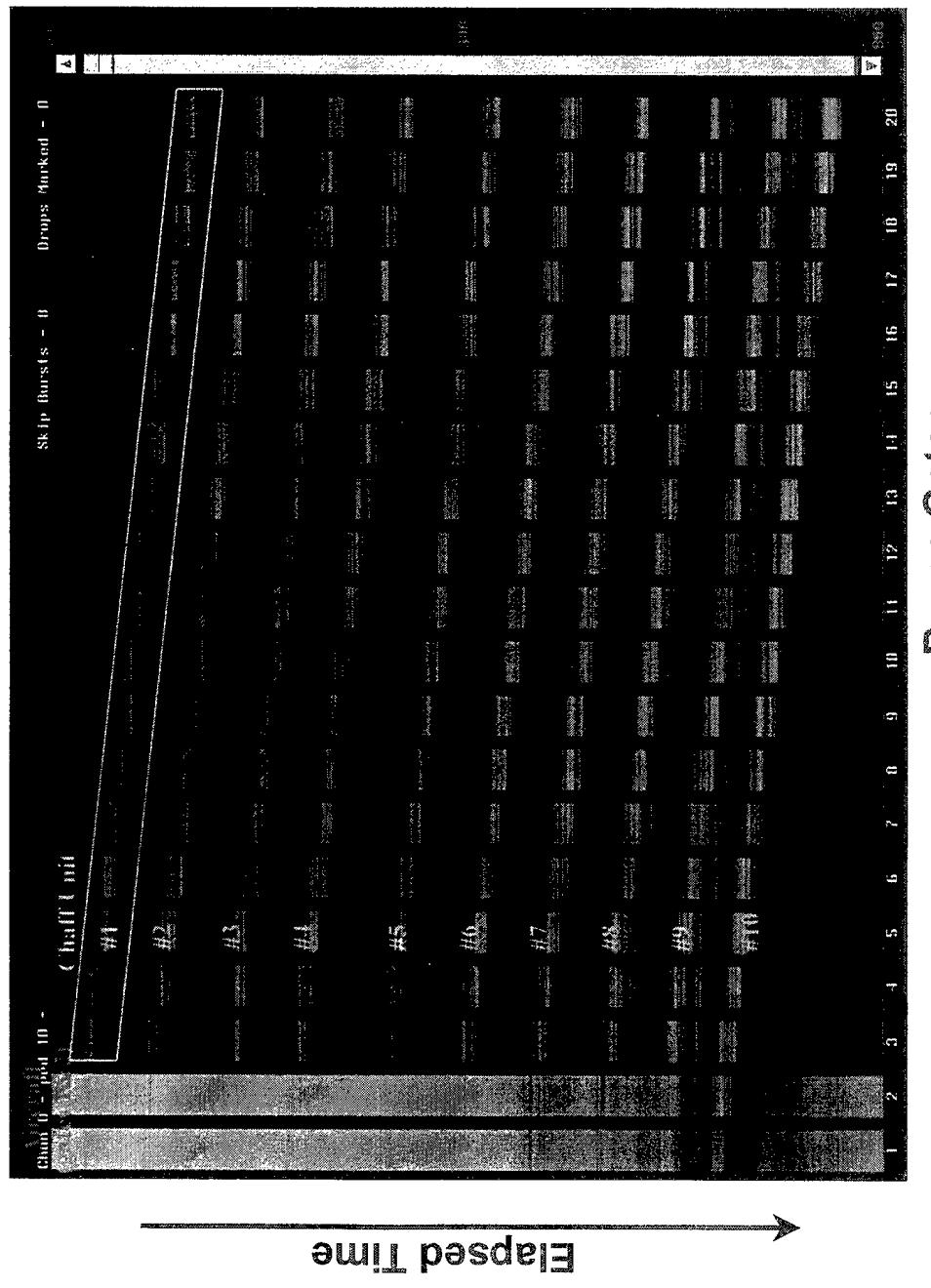


# Chaff Measurements Sample Data Product - RF Spectrum





# Chaff Measurements Sample Data Product - Shado



## Range Gates



## Extensive Signature Data Library

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- ❖ Over 50 Platforms On-Line
  - Various Platform Configurations
- ❖ Multiple Frequencies Available
  - 150 MHz to 35 GHz
- ❖ Wide Elevation Coverage
  - $\pm 45^\circ$  Elevation 360° Azimuth
- ❖ VV and HH Polarizations
- ❖ Data Available to Authorized Users



## For More Information...

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